

Benchmarking the (1+1)-ES with One-Fifth Success rule on the BBOB-2009 Noisy Testbed

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ABSTRACT

The (1+1)-ES with one-fifth success rule is one of the first and simplest stochastic algorithm proposed for optimization on a continuous search space in a black-box scenario. In this paper, we benchmark an independent-restart (1+1)-ES with one-fifth success rule on the BBOB-2009 noisy testbed. The maximum number of function evaluations used equals 10^6 times the dimension of the search space. The algorithm could only solve 3 functions with moderate noise in 5-D and 2 functions in 20-D.

Categories and Subject Descriptors

G.1.6 [Numerical Analysis]: Optimization—*global optimization, unconstrained optimization*; F.2.1 [Analysis of Algorithms and Problem Complexity]: Numerical Algorithms and Problems

General Terms

Algorithms

Keywords

Benchmarking, Black-box optimization, Evolutionary computation

1. INTRODUCTION

The (1+1)-ES with one-fifth success rule is one of the earliest and simplest adaptive stochastic search algorithm [8, 7, 3]. This paper complements [1] where an independent-restart implementation of the (1+1)-ES with one-fifth success rule is benchmarked on the BBOB-2009 noise-free testbed. Indeed, we test exactly the same algorithm, using the same settings on the BBOB-2009 noisy testbed. For the description of the algorithm and the settings we refer to [1].

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2. RESULTS AND DISCUSSION

Results from experiments according to [5] on the benchmark functions given in [4, 6] are presented in Figures 1 and 2 and in Tables 1 and 2.

We observe that globally the algorithm performs poorly. In 5-D, only f_{101} , f_{102} , f_{103} are solved and in 20-D only f_{101} and f_{102} are solved. The functions solved belong to the class of functions with moderate noise.

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3. REFERENCES

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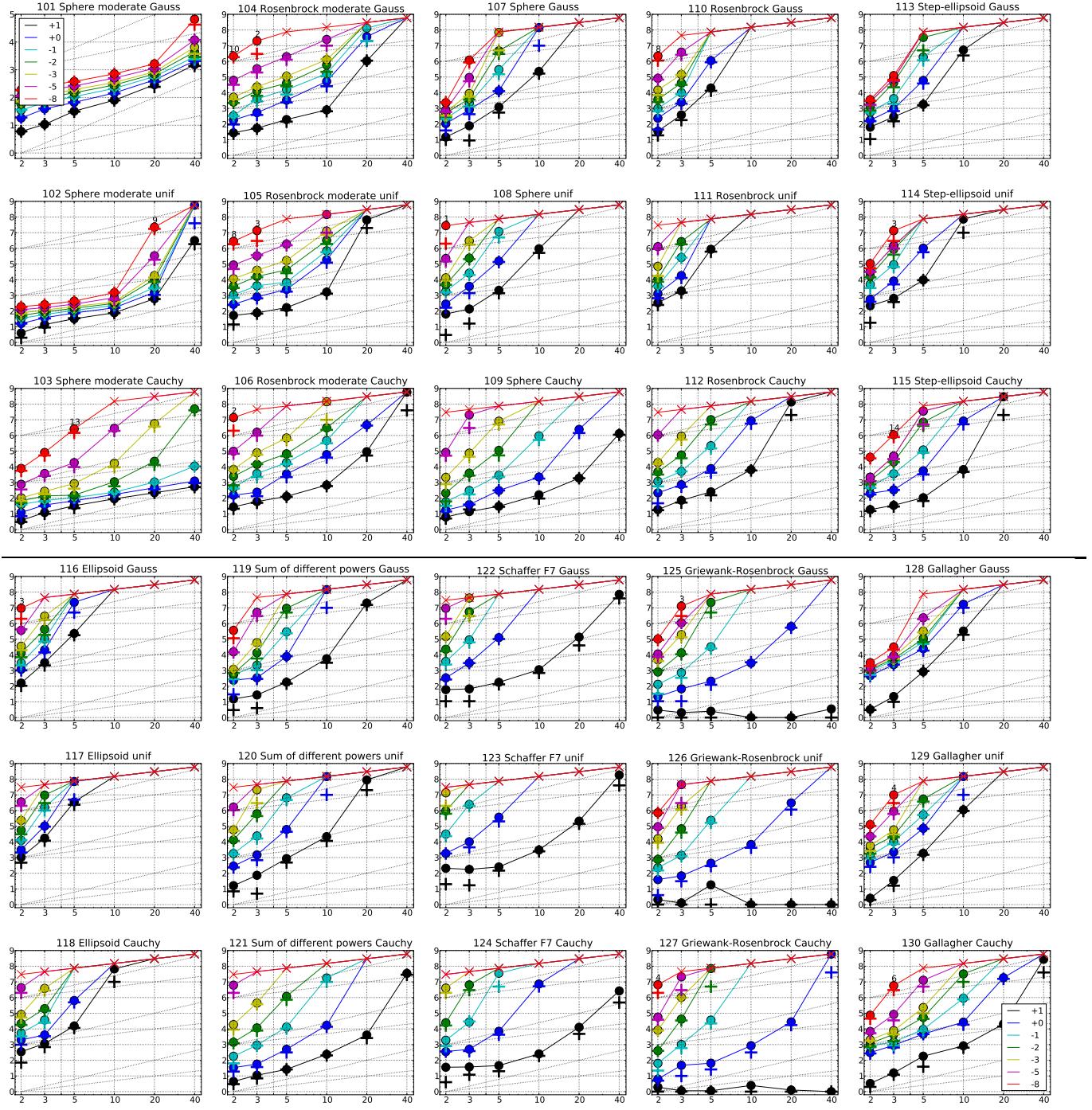


Figure 1: Expected Running Time (ERT, ●) to reach $f_{\text{opt}} + \Delta f$ and median number of function evaluations of successful trials (+), shown for $\Delta f = 10, 1, 10^{-1}, 10^{-2}, 10^{-3}, 10^{-5}, 10^{-8}$ (the exponent is given in the legend of f_{101} and f_{130}) versus dimension in log-log presentation. The $\text{ERT}(\Delta f)$ equals to $\#\text{FEs}(\Delta f)$ divided by the number of successful trials, where a trial is successful if $f_{\text{opt}} + \Delta f$ was surpassed during the trial. The $\#\text{FEs}(\Delta f)$ are the total number of function evaluations while $f_{\text{opt}} + \Delta f$ was not surpassed during the trial from all respective trials (successful and unsuccessful), and f_{opt} denotes the optimal function value. Crosses (+) indicate the total number of function evaluations $\#\text{FEs}(-\infty)$. Numbers above ERT-symbols indicate the number of successful trials. Annotated numbers on the ordinate are decimal logarithms. Additional grid lines show linear and quadratic scaling.

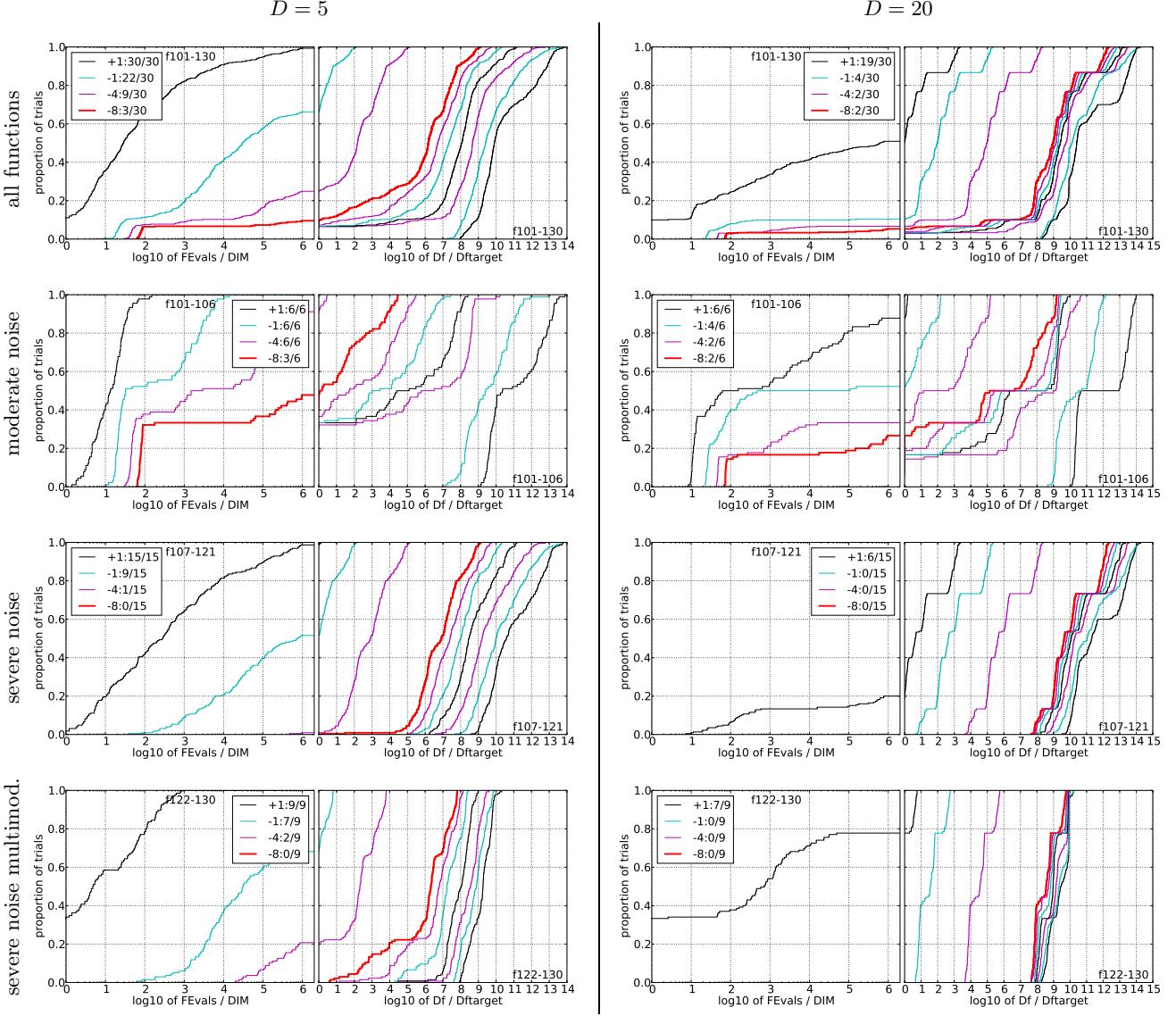


Figure 2: Empirical cumulative distribution functions (ECDFs), plotting the fraction of trials versus running time (left subplots) or versus Δf (right subplots). The thick red line represents the best achieved results. Left subplots: ECDF of the running time (number of function evaluations), divided by search space dimension D , to fall below $f_{\text{opt}} + \Delta f$ with $\Delta f = 10^k$, where k is the first value in the legend. Right subplots: ECDF of the best achieved Δf divided by 10^k (upper left lines in continuation of the left subplot), and best achieved Δf divided by 10^{-8} for running times of $D, 10D, 100D \dots$ function evaluations (from right to left cycling black-cyan-magenta). Top row: all results from all functions; second row: moderate noise functions; third row: severe noise functions; fourth row: severe noise and highly-multimodal functions. The legends indicate the number of functions that were solved in at least one trial. FEvals denotes number of function evaluations, D and DIM denote search space dimension, and Δf and Df denote the difference to the optimal function value.

