

# AMaLGaM IDEAs in Noiseless Black-Box Optimization Benchmarking

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## ABSTRACT

This paper describes the application of a Gaussian Estimation-of-Distribution (EDA) for real-valued optimization to the noiseless part of a benchmark introduced in 2009 called BBOB (Black-Box Optimization Benchmarking). Specifically, the EDA considered here is the recently introduced parameter-free version of the Adapted Maximum-Likelihood Gaussian Model Iterated Density-Estimation Evolutionary Algorithm (AMaLGaM-IDEA). Also the version with incremental model building (iAMaLGaM-IDEA) is considered.

## Categories and Subject Descriptors

G.1.6 [Numerical Analysis]: Optimization Global Optimization, Unconstrained Optimization; F.2.1 [Analysis of Algorithms and Problem Complexity]: Numerical Algorithms and Problems

## General Terms

Algorithms

## Keywords

Benchmarking, Black-box optimization, Evolutionary computation

## 1. METHOD

Estimation-of-distribution algorithms (EDAs) [7, 8] are an important strand of research on black-box optimization (BBO). EDAs attempt to automatically exploit features of a problem's structure by probabilistically modeling the search space based on previously evaluated solutions and generating new solutions by sampling the probabilistic model.

The general EDA procedure is as follows. A population  $\mathcal{P}$  of  $n$  solutions is maintained. Through selection, a vector  $\mathcal{S}$  is selected from  $\mathcal{P}$ . A probability distribution over the solution space is then estimated using  $\mathcal{S}$  as a data set. New

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solutions are generated by sampling the estimated probability distribution. Finally, the newly generated samples are incorporated into the population and the process repeats until a termination criterion has been satisfied.

The EDA considered here is the Adapted Maximum-Likelihood Gaussian Model Iterated Density-Estimation Evolutionary Algorithm (AMaLGaM-IDEA, or AMaLGaM for short). In AMaLGaM, the probability distribution used is the normal, also known as the Gaussian, distribution. This EDA uses maximum-likelihood estimates for the mean and the covariance matrix, estimated from the selected solutions. It has a mechanism that scales up the covariance matrix when required to prevent premature convergence on slopes. It furthermore has a mechanism that anticipates the mean shift in the next generation to speed up descent (in case of minimization) along slopes. For a more extensive description, we refer the interested reader to the literature [1].

In addition to the above base procedure, recently a parameter-free version of AMaLGaM was introduced [3]. After experimental analysis, settings were proposed for all parameters. Guidelines were developed for the minimally required population size that allows unimodal problems to be solved. On multimodal problems a restart mechanism is required to increase the probability of success. The specific restart scheme considered increases the number of solutions upon each restart by alternating between two approaches: a single run with a larger population and more parallel runs. To maximize the joint global effect of the parallel runs, their locality is increased by starting them in separate regions that are obtained from clustering the search space first. When increasing the number of parallel runs, the subpopulation size is also increased slightly so as to increase the robustness of the more localized searches.

Distribution estimation in AMaLGaM is done anew from scratch each generation. Subsequent iterations however have much in common and therefore the required population size can be reduced by incremental learning, i.e. combining the distribution estimated from  $\mathcal{S}$  with the distribution used in the previous generation. In iAMaLGaM a memory-decay approach is taken to this end. On unimodal problems the required population size was found to indeed be significantly reduced while at the same time requiring less function evaluations to reach the same solution quality. Results on multimodal landscapes indicated however that if memory resources are not very important, a larger base-population size helps

in optimizing multimodal problems, thus favoring the non-incremental approach. For this reason we tested both AMaLGaM and iAMaLGaM on the BBOB benchmark.

Next to the full covariance matrix, two other versions of AMaLGaM exist that reduce the number of distribution parameters to be estimated. One version uses Bayesian factorizations to select only the most important covariances while another version allows only variances. If only a few dependencies between problem variables exist, these methods outperform the use of the full covariance matrix in asymptotic complexity for the scalability in terms of required function evaluations and required time. These restrictions however also render the EDA non-rotationally invariant and therefore less generally applicable. For this reason and for the sake of space, we do not submit these variants to the BBOB benchmark here. A closer look at the differences with the full covariance matrix can be found in [3]; BBOB benchmarks for additional variants are given in [2].

For technical completeness, pseudo-code is presented below. A note on the pseudo-code: in iAMaLGaM, for  $\hat{\Sigma}(0)$  a matrix with the ML variances on the diagonal and zeros off the diagonal is used. Also,  $\hat{\mu}^{\text{Shift}}(t)$  is non-existent for  $t = 0$  and for  $t = 1$  it is  $\hat{\mu}(1) - \hat{\mu}(0)$ . SDR stands for standard-deviation ratio, NIS stands for no-improvement stretch.

```
(i)AMaLGaM-Free
1 s ← 0; nBase ← 17 + 3D1.5 (iAMaLGaM: nBase ← 10D0.5)
2 do
3 if (s mod 2) = 0 then n ← (1 + s/2)nBase; p ← 2s/2
5 else n ← 21+s/2nBase; p ← 1
6 Run (i)AMaLGaM with population size n and p parallel runs,
starting from the clustering of np randomly generated solutions
into p clusters and using ηDEC ← 0.9; ηINC ← 1/ηDEC; θSDR ← 1;
τ ← 0.35; αAMS ←  $\frac{1}{2}\tau(n/(n-1))$ ; δAMS ← 2; NISMAX ← 25 + D
7 s ← s + 1
8 while optimum not found and max. eval. not reached

(i)AMaLGaM
1 ηΣ ← 1; ηShift ← 1
  (iAMaLGaM: ηΣ ←  $1 - e^{-1.1[\tau n]^{1.2}/D^{1.6}}$ ; ηShift ←  $1 - e^{-1.2[\tau n]^{0.31}/D^{0.50}}$ )
2 cMultipplier ← 1; nAMS ← αAMS(n - 1); NIS ← 0; t ← 0
3 do
4   S ← the best  $\lfloor \tau n \rfloor$  solutions in  $\mathcal{P}$  (truncation selection)
5    $\hat{\mu}(t) \leftarrow \frac{1}{|S|} \sum_{i=0}^{|S|-1} S_i$ 
6    $\hat{\Sigma}(t) \leftarrow (1 - \eta^{\Sigma}) \hat{\Sigma}(t-1) + \eta^{\Sigma} \frac{1}{|S|} \sum_{i=0}^{|S|-1} (S_i - \hat{\mu}(t))(S_i - \hat{\mu}(t))^T$ 
7    $\hat{\mu}^{\text{Shift}}(t) \leftarrow (1 - \eta^{\text{Shift}}) \hat{\mu}^{\text{Shift}}(t-1) + \eta^{\text{Shift}} (\hat{\mu}(t) - \hat{\mu}(t-1))$ 
8    $\hat{\mu} \leftarrow \hat{\mu}(t)$ ;  $\hat{\Sigma} \leftarrow c^{\text{Multiplier}} \hat{\Sigma}(t)$ ;  $\mathbf{L}\mathbf{L}^* \leftarrow$  Cholesky decom. of  $\hat{\Sigma}$ 
9    $\mathcal{P}_0 \leftarrow$  the best solution in S
10   $\mathcal{P}_{1\dots n-1} \leftarrow n - 1$  samples from  $\mathcal{N}(\hat{\mu}, \hat{\Sigma}) = \hat{\mu} + \mathbf{L}\mathcal{N}(\mathbf{0}, \mathbf{I})$ 
11  for nAMS random solutions  $\mathcal{P}_j$  ( $1 \leq j \leq n - 1$ )
12  do  $\mathcal{P}_j \leftarrow \mathcal{P}_j + \delta^{\text{AMS}} c^{\text{Multiplier}} \hat{\mu}^{\text{Shift}}(t)$ 
13  if any  $\mathcal{P}_i$  better than  $\mathcal{P}_0$  ( $1 \leq i \leq n - 1$ )
14  then
15    NIS ← 0
16    if  $c^{\text{Multiplier}} < 1$  then  $c^{\text{Multiplier}} \leftarrow 1$ 
17     $\mathbf{x}^{\text{avg-imp}} \leftarrow$  average of all  $\mathcal{P}_i$  better than  $\mathcal{P}_0$  ( $1 \leq i \leq n - 1$ )
18    SDR ←  $\max_{1 \leq i \leq D-1} \{ |(\mathbf{L}^{-1}(\mathbf{x}^{\text{avg-imp}} - \hat{\mu}))_i| \}$ 
19    if SDR > θSDR then  $c^{\text{Multiplier}} \leftarrow \eta^{\text{INC}} c^{\text{Multiplier}}$ 
20  else
21    if  $c^{\text{Multiplier}} \leq 1$  then NIS ← NIS + 1
22    if ( $c^{\text{Multiplier}} > 1$ ) or (NIS ≥ NISMAX)
23    then  $c^{\text{Multiplier}} \leftarrow \eta^{\text{DEC}} c^{\text{Multiplier}}$ 
24    if ( $c^{\text{Multiplier}} < 1$ ) and (NIS < NISMAX) then  $c^{\text{Multiplier}} \leftarrow 1$ 
25    t ← t + 1
27 while opt. not found, max. eval. not reached and  $c^{\text{Multiplier}} \geq 10^{-10}$ 
```

## 2. PARAMETERS AND OTHER SETTINGS

For initialization, a uniform sampling in  $[-5, 5]^D$  was used, where  $D$  denotes the dimension of the search space. The experiments according to [5] on the benchmark functions given in [4, 6] have been conducted using the provided C-code.

The AMaLGaM implementation used is also in C. A maximum of  $10^6 D$  function evaluations is allowed. No changes were made to parameter-free AMaLGaM as described in [3] and as outlined above. Therefore no parameter tuning was required and the crafting effort CrE [5] is zero.

## 3. CPU TIMING EXPERIMENT

For the timing experiment the full covariance matrix variant for both AMaLGaM and iAMaLGaM were run with a maximum of  $10^6 D$  function evaluations and restarted until 30 seconds had passed (according to Figure 2 in [5]). The experiments have been conducted on an Intel Q6600 Core2Quad 2.4 GHz processor under Fedora Linux release 10 (Cambridge). In 2, 3, 5, 10, 20 and 40 dimensions, the time in  $10^{-7}$  seconds per function evaluation was as follows:

	2	3	5	10	20	40
AMaLGaM	1.9	2.2	3.0	5.0	10	24
iAMaLGaM	1.9	2.3	3.0	5.3	11	29

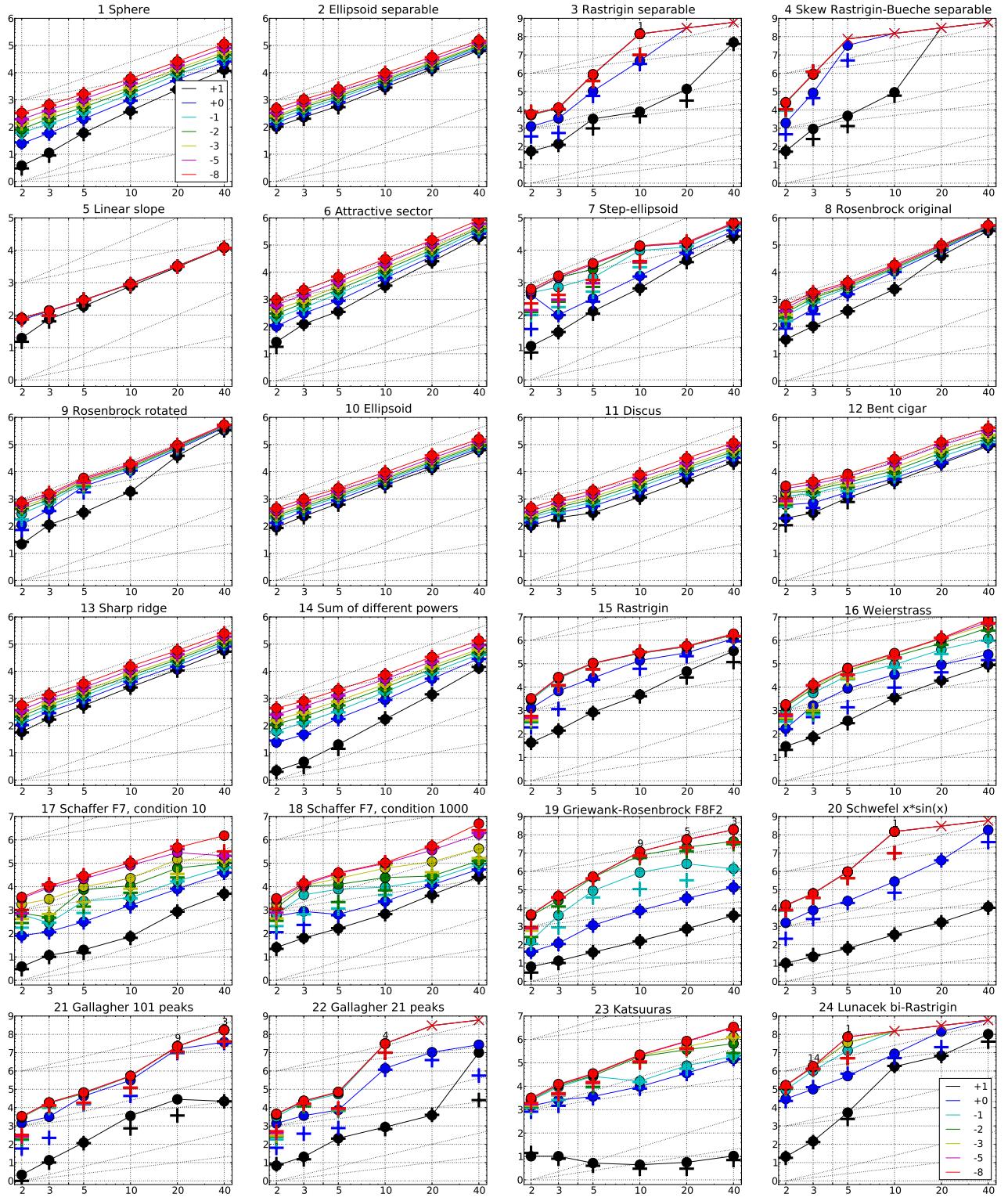
## 4. RESULTS AND CONCLUSION

Results from experiments according to [5] on the benchmark functions given in [4, 6] are presented in Figures 1 and 2 and in Table 1 for AMaLGaM and in Figures 3 and 4 and in Table 2 for iAMaLGaM.

Problems with weak structure appear to be the hardest for (i)AMaLGaM. Even within  $10^6 D$  evaluations the optimum cannot be found within a desirable precision, especially for larger  $D$ . The difference between AMaLGaM and iAMaLGaM is not large which supports the design of the population-size reducing incremental-learning approach used. Consistent with earlier findings, the incremental approach is better on unimodal functions, whereas the non-incremental approach is (slightly) better on multimodal functions, most likely due to the larger base population-size.

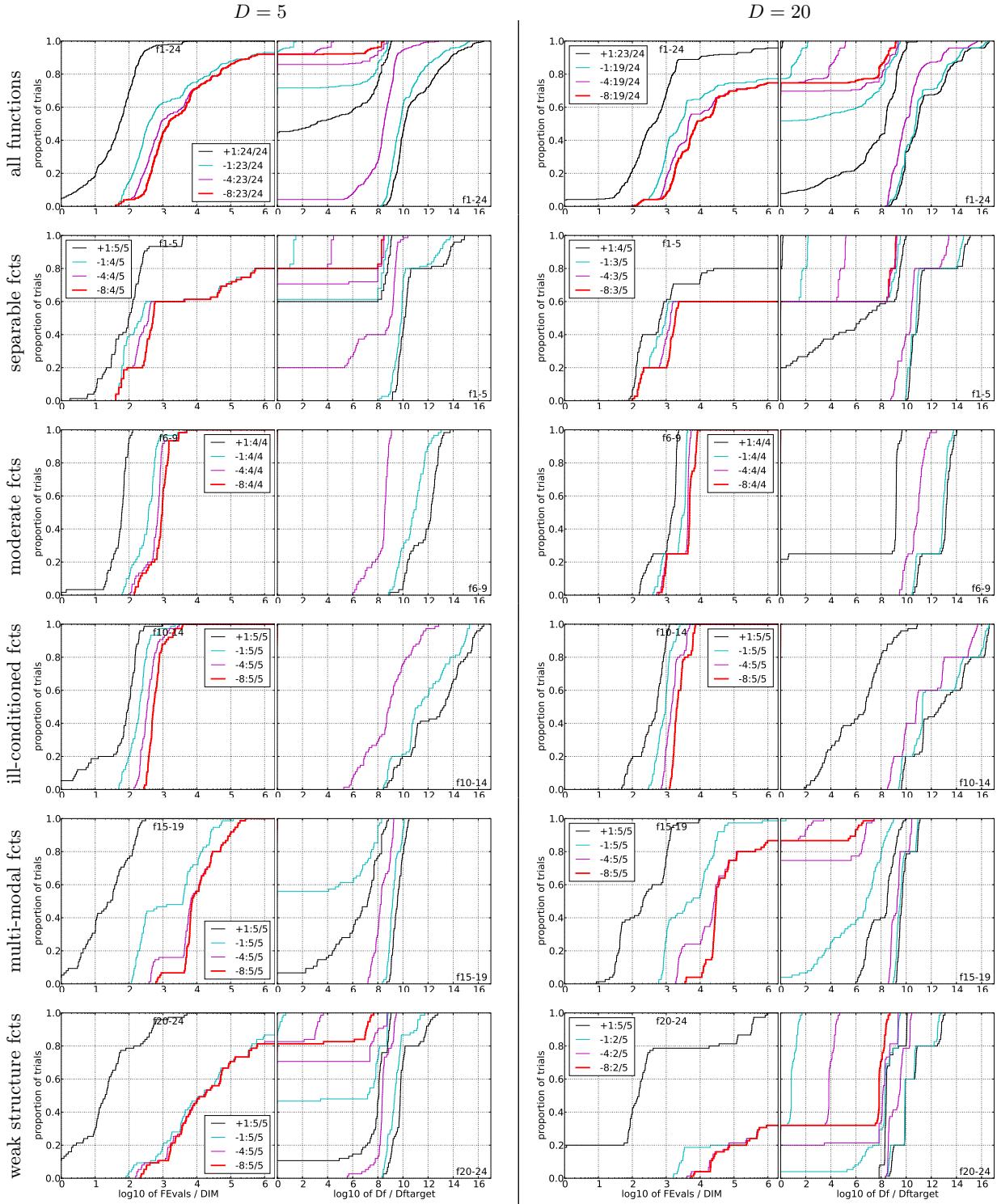
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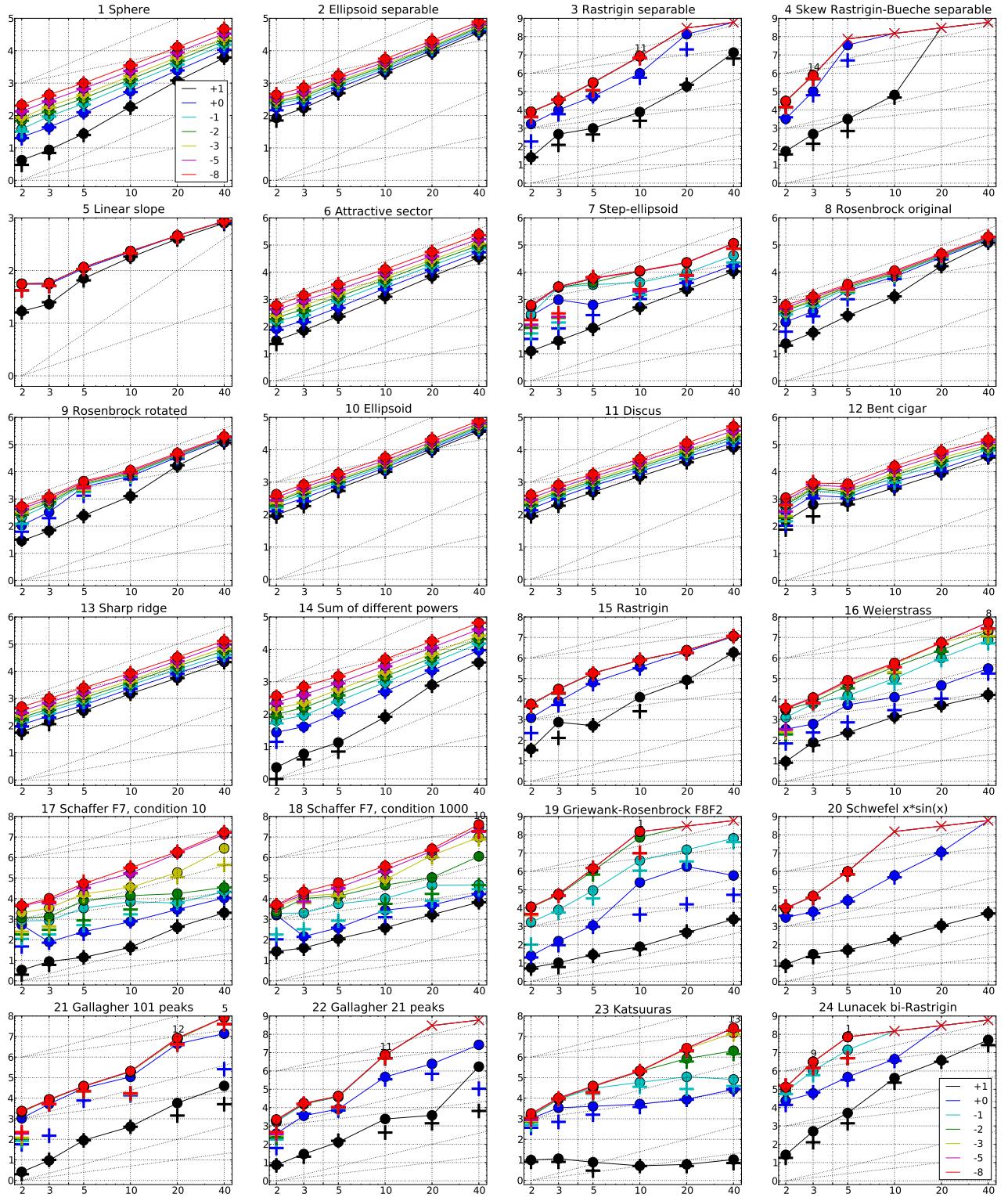


**Figure 1: AMaLGaM: Expected Running Time (ERT, ●) to reach  $f_{\text{opt}} + \Delta f$  and median number of function evaluations of successful trials (+), shown for  $\Delta f = 10, 1, 10^{-1}, 10^{-2}, 10^{-3}, 10^{-5}, 10^{-8}$  (the exponent is given in the legend of  $f_1$  and  $f_{24}$ ) versus dimension in log-log presentation. The  $\text{ERT}(\Delta f)$  equals to  $\#\text{FEs}(\Delta f)$  divided by the number of successful trials, where a trial is successful if  $f_{\text{opt}} + \Delta f$  was surpassed during the trial. The  $\#\text{FEs}(\Delta f)$  are the total number of function evaluations while  $f_{\text{opt}} + \Delta f$  was not surpassed during the trial from all respective trials (successful and unsuccessful), and  $f_{\text{opt}}$  denotes the optimal function value. Crosses (×) indicate the total number of function evaluations  $\#\text{FEs}(-\infty)$ . Numbers above ERT-symbols indicate the number of successful trials. Annotated numbers on the ordinate are decimal logarithms. Additional grid lines show linear and quadratic scaling.**



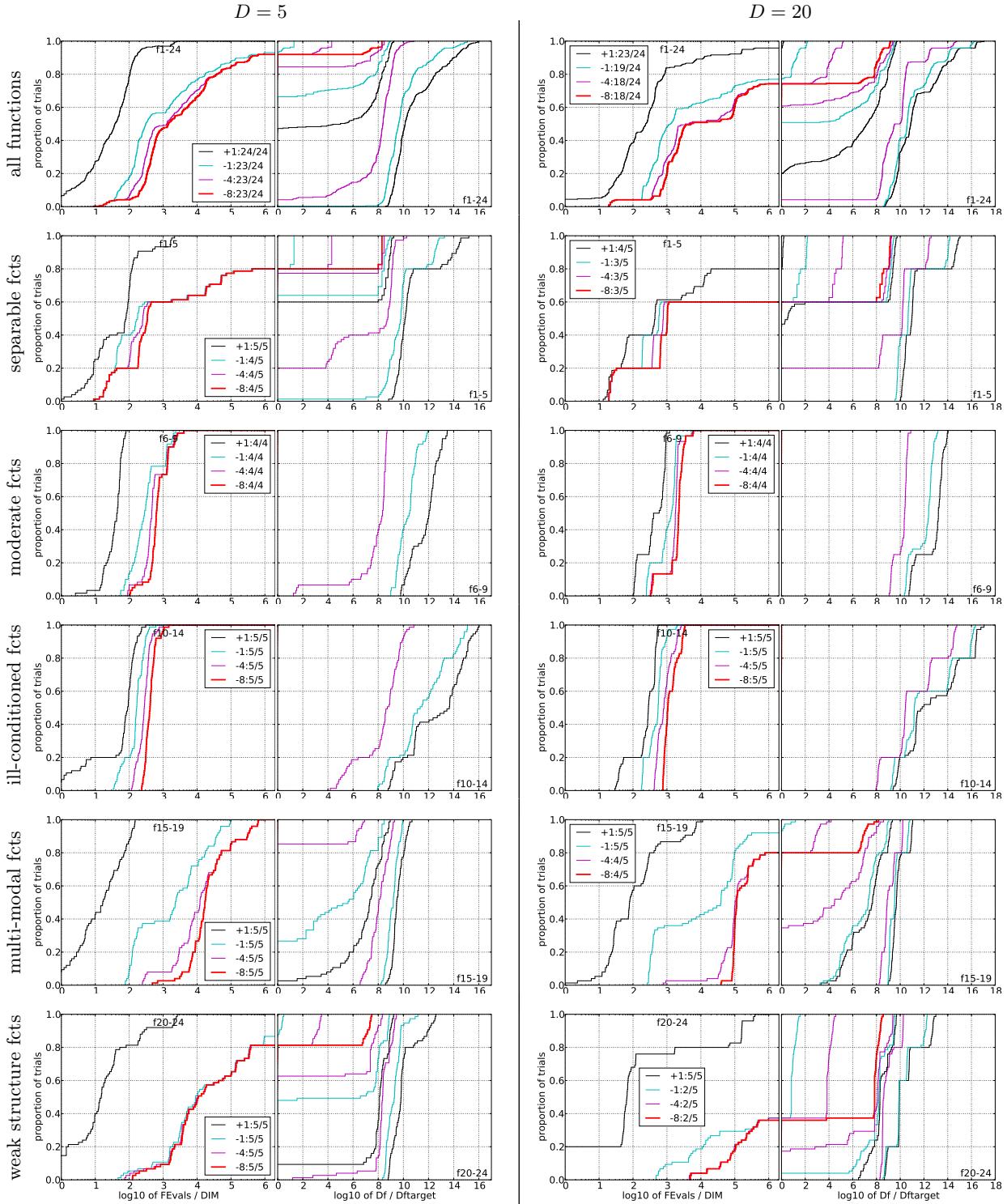


**Figure 2: AMaLGaM: Empirical cumulative distribution functions (ECDFs), plotting the fraction of trials versus running time (left) or  $\Delta f$ . Left subplots: ECDF of the running time (number of function evaluations), divided by search space dimension  $D$ , to fall below  $f_{\text{opt}} + \Delta f$  with  $\Delta f = 10^k$ , where  $k$  is the first value in the legend. Right subplots: ECDF of the best achieved  $\Delta f$  divided by  $10^k$  (upper left lines in continuation of the left subplot), and best achieved  $\Delta f$  divided by  $10^{-8}$  for running times of  $D, 10D, 100D\dots$  function evaluations (from right to left cycling black-cyan-magenta). Top row: all results from all functions; second row: separable functions; third row: misc. moderate functions; fourth row: ill-conditioned functions; fifth row: multi-modal functions with adequate structure; last row: multi-modal functions with weak structure. The legends indicate the number of functions that were solved in at least one trial. FEval denotes number of function evaluations,  $D$  and DIM denote search space dimension, and  $\Delta f$  and Df denote the difference to the optimal function value.**



**Figure 3: iAMaLGaM: Expected Running Time (ERT, ●) to reach  $f_{\text{opt}} + \Delta f$  and median number of function evaluations of successful trials (+), shown for  $\Delta f = 10, 1, 10^{-1}, 10^{-2}, 10^{-3}, 10^{-5}, 10^{-8}$  (the exponent is given in the legend of  $f_1$  and  $f_{24}$ ) versus dimension in log-log presentation. The  $\text{ERT}(\Delta f)$  equals to  $\#\text{FEs}(\Delta f)$  divided by the number of successful trials, where a trial is successful if  $f_{\text{opt}} + \Delta f$  was surpassed during the trial. The  $\#\text{FEs}(\Delta f)$  are the total number of function evaluations while  $f_{\text{opt}} + \Delta f$  was not surpassed during the trial from all respective trials (successful and unsuccessful), and  $f_{\text{opt}}$  denotes the optimal function value. Crosses (x) indicate the total number of function evaluations  $\#\text{FEs}(-\infty)$ . Numbers above ERT-symbols indicate the number of successful trials. Annotated numbers on the ordinate are decimal logarithms. Additional grid lines show linear and quadratic scaling.**





**Figure 4: iAMaLGaM: Empirical cumulative distribution functions (ECDFs), plotting the fraction of trials versus running time (left) or  $\Delta f$ . Left subplots: ECDF of the running time (number of function evaluations), divided by search space dimension  $D$ , to fall below  $f_{\text{opt}} + \Delta f = 10^k$ , where  $k$  is the first value in the legend. Right subplots: ECDF of the best achieved  $\Delta f$  divided by  $10^k$  (upper left lines in continuation of the left subplot), and best achieved  $\Delta f$  divided by  $10^{-8}$  for running times of  $D, 10D, 100D \dots$  function evaluations (from right to left cycling black-cyan-magenta). Top row: all results from all functions; second row: separable functions; third row: misc. moderate functions; fourth row: ill-conditioned functions; fifth row: multi-modal functions with adequate structure. The legends indicate the number of functions that were solved in at least one trial. FEvals denotes number of function evaluations,  $D$  and DIM denote search space dimension, and  $\Delta f$  and  $Df$  denote the difference to the optimal function value.**